# NCS4000系统ECU到ECU2的CLI迁移过程

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## 简介

本文档介绍成功交换安装在NCS4016系统中的在用外部连接单元(ECU)并替换为ECU 2所需的信息。该过程提供了拆卸/安装ECU的步骤。

## 先决条件

### 要求

Cisco 建议您了解以下主题:

- 用于Cisco NCS4000系列的CLI Cisco IOS®
- •思科NCS4000系列,包括NCS4016/NCS4009

### 使用的组件

本文档中的信息基于在开始此过程之前运行6.5.26或更高版本软件的NCS4016系统。

本文档中的信息都是基于特定实验室环境中的设备编写的。本文档中使用的所有设备最初均采用原 始(默认)配置。如果您的网络处于活动状态,请确保您了解所有命令的潜在影响。

## 背景信息

本文档中详述的过程不会影响流量。它假设NCS4000机箱是4016或4009机架。如果您的网络处于 活动状态,请确保您了解所有命令的潜在影响。

## 建立与NCS4K的连接并验证6.5.26的最低软件版本

开始之前,请确保已设置与NCS 4016的笔记本电脑连接,且笔记本电脑符合硬件和软件要求。

步骤1.从连接到NCS 4016机架的计算机启动终端仿真程序(如putty)并登录NCS4016系统。

步骤2.在命令提示符下,执行show version,并验证软件版本是否为6.5.26,如图所示。

```
RP/0/RP0:Node_Name#show version
Thu Nov 14 13:44:09.282 CST
Cisco IOS XR Software, Version 6.5.26
Copyright (c) 2013-2019 by Cisco Systems, Inc.
Build Information:
Built By : ahoang
Built On : Fri Sep 13 13:33:51 PDT 2019
Built Host : iox-lnx-060
Workspace : /auto/srcarchive11/prod/6.5.26/ncs4k/ws
Version : 6.5.26
Location : /opt/cisco/XR/packages/
cisco NCS-4000 () processor
```

System uptime is 2 weeks 5 days 21 hours 42 minutes

步骤3.如果软件不在6.5.26或更高版本上,请停止该过程并将软件升级到6.5.26,然后再继续。

#### 步骤4.验证并记录图中所示的所有警报。

RP/0/RP <u>0:Node_</u> Thu Nov 14 13:5	Name# <mark>show alaı</mark> 53:08.689 CST	rms brief system a	lctive	
Active Alarms				
Location	Severity	Group	Set Time	Description
0/12 0/0 0/0 0/6 0/3 0/6 0/3 0/4 0/0 0/3 0/2 0/0 0/0 0/0 0/0 RP/0/RP0:Node N	Critical Minor Minor Critical Critical Critical Major Critical Major Critical Critical Critical Critical Critical	Environ Controller Controller Controller OTN OTN Ethernet Ethernet Ethernet Ethernet OTN OTN OTN	10/20/2019 21:30:42 CDT 10/20/2019 21:31:45 CDT 10/20/2019 21:31:45 CDT 10/20/2019 21:31:53 CDT 10/20/2019 21:31:57 CDT 10/20/2019 21:32:59 CDT 10/20/2019 21:33:02 CDT 10/21/2019 16:41:56 CDT 10/25/2019 17:11:10 CDT 11/01/2019 10:32:48 CDT 10/30/2019 05:41:09 CDT 11/01/2019 10:34:57 CDT 11/01/2019 10:34:59 CDT	LC12 - Improper Removal Optics0/0/0/0/5 - Optics Low Transmit Power Optics0/0/0/0/6 - Optics Low Transmit Power Optics0/3/0/6 - Optics Unqualified PPM ODU40/6/0/10 - OPUK Client Signal Failure ODU40/3/0/10 - OPUK Client Signal Failure TenGigECtrlr0/4/0/0/2 - Carrier Loss On The LAN TenGigECtrlr0/2/0/4/1 - Local Fault OTU40/3/0/11 - Incoming Payload Signal Absent TenGigECtrlr0/2/0/4/1 - Carrier Loss On The LAN TenGigECtrlr0/0/0/0/2 - Carrier Loss On The LAN TenGigECtrlr0/0/0/0/2 - Carrier Loss On The LAN ODU20/0/0/0/1 - OPUK Client Signal Failure ODU20/0/0/0/2 - OPUK Client Signal Failure

步骤5.检验硬盘详细信息。

sysadmin-vm:0\_RP0# sh media

Fri Jun 21 20:21:28.615 UTC

Partition	Size	Used	Percent	Avail	
rootfs:	2.4G	633M	29%	1.6G	
log:	478M	308M	70%	135M	
config:	478M	32M	88	410M	
disk0:	949M	47M	6%	838M	
install:	3.7G	2.8G	81%	681M	
disk1:	18G	3.0G	18%	14G	

\_\_\_\_\_

rootfs: = root file system (read-only) log: = system log files (read-only) config: = configuration storage (read-only) install: = install repository (read-only) sysadmin-vm:0\_RPO#

#### 步骤6.创建数据库备份。

```
RP/0/RP0:Node_Name#save configuration database disk1:Node_Name_DB_BACKUP
Thu Nov 14 13:59:54.631 CST
Configuration database successfully backed up at:
/harddisk:/disk1:Node Name_DB_BACKUP.tgz
RP/0/RP0:Node_Name#show run | file_disk1:Node_Name_DB_BACKUP
Thu Nov 14 14:00:41.974 CST
Building configuration...
```

[OK] RP/0/RP<u>0:Node\_</u>Name#

步骤7.检验BITS计时。如果NCS4K使用BITS定时,请记录这些命令的输出。如果未使用计时,请 跳至步骤8。记录show controller timing controller clock命令的输出,如**图所示。**  RP/0/RP0:Node\_Name #show controller timing controller clock Wed Nov 13 14:53:18.781 CST

BITSO-IN BITSO-OUT BITS1-IN BITS1-OUT Config : Yes Yes No No PORT Mode : T1 т1 --Framing : ESF -ESF \_ Linecoding : B8ZS -B8ZS \_ -Submode : --\_ No Shutdown : No No No Direction : RX TX RX TX QL Option : 02 G1 02 G1 --02 G1 02 G1 RX\_ssm : PRS PRS --TX ssm : ---ADMIN\_DOWN If state : UP UP ADMIN DOWN TE1-E TEO-E TEO-W TE1-W Config : NA NA NA NA PORT Mode : ICS ICS ICS ICS Framing : ----Linecoding : ----Submode : ---Shutdown : No No No No Direction : ---\_ QL Option : 01 01 01 01 RX\_ssm : -TX\_ssm : ---\_ --\_ If state : DOWN DOWN DOWN DOWN

SYNCEC Clock-Setting: Rack 0

如图所示,记录show frequency synchronization clock-interfaces brief命令的输出。

RP/0/RP	0: Node_Name	show fre	quency	synchroniza	tion clock-interfaces brief
Tue Nov	5 16:38:03.711 CS	T			
Flags:	> - Up	D -	Down		S - Assigned for selection
	d - SSM Disabled	s -	0utput	squelched	L - Looped back
Node 0/	RP0:				
-1	-1				
FL	Clock Interface	QLrcv	QLuse	Pri QLsnd	Output driven by
		= ======		50 - 4-	
>5	Rack0-Bits0-In	PRS	PRS	50 n/a	n/a
D	Rack0-Bits0-Out	n/a	n/a	n/a PRS	Rack0-Bits0-In
>S	Rack0-Bits1-In	PRS	PRS	50 n/a	n/a
D	Rack0-Bits1-Out	n/a	n/a	n/a PRS	Rack0-Bits0-In
D	0/TE0-E	n/a	n/a	n/a n/a	n/a
D	0/TE1-E	n/a	n/a	n/a n/a	n/a
D	0/TE0-W	n/a	n/a	n/a n/a	n/a
D	0/TE1-W	n/a	n/a	n/a n/a	n/a
>S	Internal0	n/a	ST3	255 n/a	n/a

步骤8.准备拆除ECU。为了安全地将ECU从服务中移除,请发出detach命令**hw-module provision** ecu detach disk rack 0,如图所示。

RP/0/RP0:Node Name#hw-module provision ecu detach disk rack 0 Thu Nov 14 14:30:25.864 CST provision: detach triggered for rack :0 RP/0/RP0:Node Name#hw-module provision ecu status disk rack 0 Thu Nov 14 14:30:57.139 CST provision: status triggered for rack :0 detach: operation ongoing RP/0/RP0:Node Name# RP/0/RP0:Node Name#show alarms brief system active Thu Nov 14 14:32:51.469 CST Active Alarms \_\_\_\_\_ Location Severity Group Set Time Description \_\_\_\_\_ 
 Minor
 Software
 11/14/2019
 14:30:28
 CST

 Minor
 Software
 11/14/2019
 14:31:57
 CST
 0/RP1 disk provision is in progress 0/RP0 The detach provision for disk start RP/0/RP0:Node\_Name#

#### 步骤9.在物理移除ECU模块之前,请确保警报系统上已清除磁盘的分离操作。

RP/0/RP0:Node\_Name #hw-module provision ecu status disk rack 0
Thu Nov 14 14:36:07.406 CST
provision: status triggered for rack :0
detach: operation completed successfully

步骤10.从NCS4K机箱卸下ECU模块:

a.确保用户佩戴防静电腕带。

b.拔下连接到NCS4K-ECU模块的所有电缆。

c.移除EMS电缆时,会将所有远程管理丢弃到机架中。在步骤11中重新连接EMS电缆后,它才会恢 复。使用控制台端口仍可实现远程访问。

e.拔下连接到设备的所有单独定时电缆。

f.使用飞利浦螺丝刀拧松ECU单元上的螺钉。

g.使用两侧的锁闩将NCS4K-ECU单元插出。

h从原始NCS4K-ECU中卸下两个2.5英寸SATA驱动器(SSD)。注意ECU中的确切位置(左或右)。

我。将从NCS4K-ECU卸下的2.5英寸SATA驱动器插入新的NCS4K-ECU2模块。确保它们安装在与 原始ECU相同的位置。

步骤11.安装ECU2模块并重新连接电缆:

a.将新的NCS4K-ECU2模块(两个2.5英寸SATA驱动器)放入原始ECU插槽中。

b.将步骤10中移除的所有电缆重新连接到新的ECU2模块。

c.正确定位闩锁后拧紧螺钉。

d.确保与NE的远程管理连接再次可用。

#### e.确保NE的前面板LCD工作正常。



步骤12.在NCS4K机箱中初始化新的ECU2。等待2到3分钟,NCS4K-ECU2模块初始化。

步骤13.如图所示,在命令提示符下执行attach命令。

```
RP/0/RP0:Node_Name#hw-module provision ecu attach disk rack 0
Thu Nov 14 14:47:05.299 CST
provision: attach triggered for rack :0
RP/0/RP0:Node_Name#hw-module provision ecu status disk rack 0
Thu Nov 14 14:47:49.869 CST
provision: status triggered for rack :0
attach: operation ongoing
RP/0/RP0:Node_Name#hw-module provision ecu status disk rack 0
Thur Nov 14 14:50:13.884 CST
provision: status triggered for rack :0
attach: operation completed successfully
RP/0/RP0:Node_Name#
```

步骤14.一旦ECU成功连接到机箱,ECU从NCS4K-ECU迁移到NCS4K-ECU2完成。

### 过帐检查

#### 验证警报

验证警报并确保机架上没有新警报或意外警报。

**注意:**对于RP0和RP1,位置警报的磁盘空间警报可能需要稍长的时间才能空闲,但您可以使用sh media命令验证磁盘是否运行正常。

Tal	b View																		
A	arms	Condi	tions	History Circuits	Provisioning	Inventory	Ma	intena	nce										_
1	lum R	ef Ne	w	Date	Object	Eqpt Type	Slot	Unit	Port	Wavelength	Path Width	Sev	ST	SA	Cond	Description	Direction	Location	
	NA N	A 🗸	·	06/21/19 14:40:34	0/RP0	Route Pr	RP0		NA	NA	NA	CR	С	NA	DISK1-DISK-SPA	Disk space alert for location "Sysadmin:/mis	NA	NEAR	-
IF	NA N	Α 🗸	·	06/21/19 14:40:01	0/RP0	Route Pr	RP0		NA	NA	NA	MN	С	NA	ECU_CAL_DISK	disk provision is in progress	NA	NEAR	
IF	NA N	A 🗸	'	06/21/19 14:40:00	0/RP0	Route Pr	RPO		NA	NA	NA	MN	С	NA	ECU_CAL_PROV	The attach provision for disk started	NA	NEAR	

Tab	View																		· · · · · · · · · · · · · · · · · · ·	
Ali	Imms Conditions History Circuits Provisioning Inventory Maintenance																			
N	um	Ref	New	Date	Object	Eapt Type	Slot	Unit	Port	Wavelength	Path Width	Sev	ST	SA	Cond	Description	Direction	Location		-
1	A	NA	×	06/21/19 14:40:34	0/RP0	Route Pr	RPO		NA	NA	NA	CR	С	NA	DISK1-DISK-SPA	Disk space alert for location "Sysadmin:/mis	NA	NEAR		
1	A	NA	-	06/21/19 14:40:01	0/RP0	Route Pr	RPO		NA	NA	NA	MN	С	NA	ECU_CAL_DISK	disk provision is in progress	NA	NEAR	1	
1	A	NA	-	06/21/19 14:40:00	0/RP0	Route Pr	RPO		NA	NA	NA	MN	С	NA	ECU_CAL_PROV	The attach provision for disk started	NA	NEAR	1	
1	A	NA	1	06/21/19 14:38:41	0/RP0	Route Pr	RP0		NA	NA	NA	MN	R	NA	ECU_CAL_PROV	The attach provision for disk started	NA	NEAR		
P	IA	NA	NA	06/21/19 14:22:31	0/RP1	Route Pr	RP1		NA	NA	NA	CR		NA	DISK1-DISK-SPA	Disk space alert for location "Sysadmin:/mis	NA	NEAR		
1	IA	NA	NA	06/21/19 14:21:07	0/RP1	Route Pr	RP1		NA	NA	NA	MN	R	NA	ECU_CAL_DISK	disk provision is in progress	NA	NEAR		

### 验证介质

验证两个固态磁盘驱动器的插槽是否正确且是否可达,如图所示。

sysadmin-vm:0_RP0# <mark>sh media</mark>					
Fri Jun 21 20:21:28.615 UT	С				
Partition	Size	Used	Percent	Avail	
rootfs:	2.4G	633M	29%	1.6G	
log:	478M	308M	70%	135M	
config:	478M	32M	88	410M	
disk0:	949M	47M	6%	838M	
install:	3.7G	2.8G	81%	681M	
disk1:	18G	3.0G	18%	14G	
rootfs. = root file system	(read-or	<u>م</u> ا ر			

rootfs: = root file system (read-only)
log: = system log files (read-only)
config: = configuration storage (read-only)
install: = install repository (read-only)
sysadmin-vm:0\_RPO#

### BITS计时重新检查

如果已配备BITS定时,并且第1.5节已完成,请在将BITS定时重新连接到ECU2后再次运行命令,并 与图中所示的先前结果进行比较。 RP/0/RP<u>0:node\_name</u>#show\_controller\_timing\_controller\_clock Wed\_Nov\_13\_14:53:18.781\_CST

SYNCEC Clock-Setting: Rack 0

	BI	rso-in	BIT	S0-OUT	BIT	S1-IN	BIT	S1-OUT
Config	:	Yes		No		Yes	]	No
PORT Mode	:	T1		-		T1		-
Framing	:	ESF		-		ESF		-
Linecoding	: 1	B8ZS		-		B8ZS		-
Submode	:	-		-		-		-
Shutdown	:	No		No		No	]	No
Direction	:	RX		ТХ		RX	1	ТХ
QL Option	:	02 G1		O2 G1		O2 G1	(	02 G1
RX_ssm	:	PRS		-		PRS		-
TX ssm	:	-		-		-		-
If_state	:	UP		ADMIN_DOWN		UP	j	ADMIN_DOWN
		_		F				1.7
	TE(	)-Е	TE1	-E	TE0	-W	TEL	-w
Config	TE(	D-E NA	TE1	-e NA	TE0	-W NA	TEL	-w NA
Config PORT Mode	TE( :	D-E NA ICS	TE1	-E NA ICS	TE0	-W NA ICS	TEL	-w NA ICS
Config PORT Mode Framing	TE( : :	NA ICS -	TE1	-E NA ICS -	TEO	-W NA ICS -	TEL	-w NA ICS -
Config PORT Mode Framing Linecoding	TE( : : :	)-E NA ICS - -	TE1	-E NA ICS -	TEO	-W NA ICS -	TEL	-w NA ICS - -
Config PORT Mode Framing Linecoding Submode	TE( : : : :	)-Е NA ICS - -	TE1	-L NA ICS - -	TEO	-W NA ICS - -	TEL	-w NA ICS - -
Config PORT Mode Framing Linecoding Submode Shutdown	TE( : : : :	NA ICS - - No	TE1	-E NA ICS - - NO	TEO	-W NA ICS - - No		-w NA ICS - - No
Config PORT Mode Framing Linecoding Submode Shutdown Direction	TE( : : : : :	)-E NA ICS - - No -	TE1	-E NA ICS - - No -	TEO	-W NA ICS - - No -		-w NA ICS - - No -
Config PORT Mode Framing Linecoding Submode Shutdown Direction QL Option	TE(	)-Е NA ICS - - No - 01	TE1	-E NA ICS - - No - 01	TEO	-W NA ICS - - No - 01	TEL	-w NA ICS - - No - 01
Config PORT Mode Framing Linecoding Submode Shutdown Direction QL Option RX_ssm	TE(	)-Е NA ICS - - No - 01 -	TE1	-E NA ICS - - No - 01 -	TEO	-W NA ICS - - No - 01 -	1E1-	-w NA ICS - - No - 01 -
Config PORT Mode Framing Linecoding Submode Shutdown Direction QL Option RX_ssm TX_ssm	TE( : : : : : : :	)-Е NA ICS - - No - 01 -	TE1	-E NA ICS - - No - 01 -	TEO	-W NA ICS - - No - 01 -		-w NA ICS - - No - 01 -

RP/0/RP	: Node_Name #s	how free	quency s	synchronizat	tion clock-interfaces brief
Tue Nov	5 16:38:03.711 CST				
Flags:	> - Up d - SSM Disabled	D - [ s - (	Down Dutput s	squelched I	S - Assigned for selection L - Looped back
Node 0/F	RP0:				
Fl	Clock Interface	QLrcv	QLuse	Pri QLsnd	Output driven by
>S	Back0-Bits0-In	DRS	DRS	50 n/a	n/a
D	Rack0-Bits0-Out	n/a	n/a	n/a PRS	Rack0-Bits0-In
>S	Rack0-Bits1-In	PRS	PRS	50 n/a	n/a
D	Rack0-Bits1-Out	n/a	n/a	n/a PRS	Rack0-Bits0-In
D	0/TE0-E	n/a	n/a	n/a n/a	n/a
D	0/TE1-E	n/a	n/a	n/a n/a	n/a
D	0/TE0-W	n/a	n/a	n/a n/a	n/a
D	0/TE1-W	n/a	n/a	n/a n/a	n/a
>S	Internal0	n/a	ST3	255 n/a	n/a